HALMA GROUP
COMP^NY

## USERS GUIDE MATRIX <br> DIGITAL INDUCTIVE LOOP SENSORS

The MATRIX Digital Inductive Loop Detector is the ideal solution for parking barrier control, motorized gates and doors, vehicle access control and industrial control systems.
The MATRIX is a high performance single or dual-channel vehicle detector packaged in a compact housing. The connection is made with a standard industrial 11-pin round connector.
The six versions listed below include single or dual-channel, and 3 possible power supplies:

| 10MATRIXS110 | $\vdots$ | Single loop detector with 110 to 120 VAC power supply. |
| :--- | :--- | :--- |
| 10MATRIXS220 | $\vdots$ | Single loop detector with 220 to 240 VAC power supply. |
| 10MATRIXS1224 | $\vdots$ | Single loop detector with 12 to 24 VAC AC power supply. |
| 10MATRIXD110 | $\vdots$ | Dual loop detector with 110 to 120 V AC power supply. |
| 10MATRXD220 | $\vdots$ | Dual loop detector with 220 to 240 V AC power supply. |
| 10MATRIXD1224 | $:$ | Dual loop detector with 12 to $24 \mathrm{VAC} / \mathrm{DC}$ power supply. |


| TECHNICAL SPECIFICATIONS |  | ```Degree of protection:IP40 2 Output relays (free potential change-over contact) - Max contact voltage : 230 VAC ; - Max contact current : 5A (resistive). LED indicators - 1 green LED : power ; - 1 red LED : Loop status 1 ; - 1 red LED : Loop status 2. Protections : - loop insulation transformer ; - Zener diodes ; - gas discharge clamping. Connection : Standard 11-pin round connector 86CP11 Dimensions : 3 in (H) \(\times 1.5\) in (W) \(\times 3\) in (D) [ \(77 \mathrm{~mm}(\mathrm{H}) \times 40 \mathrm{~mm}(\mathrm{~W}) \times 75 \mathrm{~mm}(\mathrm{D})\) ] Weight : 7 ounces [ \(<200 \mathrm{~g}\) ] Product compliance : R\&TTE 1999/5/EC EMC 89/336/EEC FCC 47CFR15 IC RSS-210 Issue 5``` |
| :---: | :---: | :---: |

DESCRIPTION OF THE SENSOR


## SAFETY

PRECAUTIONS


- Shut off all power before attempting any wiring procedures.
- Maintain a clean \& safe environment.
- Constantly be aware of traffic around the door or gate area.
- Always suspend traffic through the doorway or gate area when performing testing that may result in unexpected reactions by the door or gate.
- Always check placement of all wiring and components before powering up to insure that moving parts will not catch any wires and cause damage to equipment.

10MATRIXS110
10MATRIXS220: Matrix, Single Unit, 220 Volt AC supply
10MATRIXS1224: Matrix, Single Unit, 12-24 Volt AC/DC supply
(FCC ID: G9B-MATRIX)
10MATRIXD110:
10MATRIXD220: Matrix, Double Unit, 110 Volt AC supply Matrix, Double Unit, 220 Volt AC supply 10MATRIXD1224: Matrix, Double Unit, 12-24 Volt AC/DC supply

(IC: 4680A-MATRIX)

The Digital Transmitters and Receivers comply with Part 15 of the FCC rules. Operation is subject to the following two conditions:

1) This device may not cause harmful interference and;
2) This device must accept any interference received including interference that may cause undesired operations.

Changes or modifications not expressly approved by B.E.A., Inc. for compliance could void the user's authority to operate the equipment.

## LOOP INSTALLATION TIPS

## A . CABLE SPECIFICATIONS FOR LOOP AND FEEDER

- 16 AWG ( $1.5 \mathrm{~mm}^{2}$ ) cross section area ;
- Multi-strand cable ;
- Insulation material : PVC or Silicone ;
- For the feeder cable, the wire must be twisted at least 15 times per yard for each cable.
- Feeder for long runs used for foil screened cable is recommended (earth at equipment end only)
- The feeder cable must be firmly fixed to avoid any false detection (max length: 330 feet ( 100 m )).
- Waterproof cable junction box is required.


## B. LOOP GEOMETRY



- When two adjacent loops are connected to a dual channel sensor, it is possible for these loops to share a common slot, if so required. As the channels are multiplexed, no interference will occur.
- Avoid large loops or long feeder [max 330 feet (100 m)], or else the sensitivity will be affected.


## C. DETERMINATION OF THE NUMBER OF LOOP TURNS

- Measure the length (L) and width (Ea) of one loop. Multiply these numbers together to determine the loop surface area. See above drawing.
- For example, if $\mathrm{L}=10 \mathrm{ft}$, $\mathrm{Ea}=3 \mathrm{ft}$, then the area $=30 \mathrm{ft}^{2} ; 4$ loop turns are recommended.
or if $\mathrm{L}=2 \mathrm{~m}$, $\mathrm{Ea}=1 \mathrm{~m}$, then the area $=2 \mathrm{~m}^{2} ; 4$ loop turns are recommended.

Recommended values for the turns:

| Area |  | Number of turns |
| :---: | :---: | :---: |
| $<32 \mathrm{ft}^{2}$ | $<3 \mathrm{~m}^{2}$ | 4 |
| $32-54 \mathrm{ft}^{2}$ | $3-5 \mathrm{~m}^{2}$ | 3 |
| $65-108 \mathrm{ft}^{2}$ | $6-10 \mathrm{~m}^{2}$ | 2 |

WARNING:
For conformity reasons, in any installation,
the loop surface multiplied by the number of
turns should not exceed 215 (for square
feet); $\mathbf{2 0}$ (for square meters)

## D. SLOT DEPTH



WARNING: Do not remove the grease on the connector's pins.


Pin 1 : Power Supply
Pin 2 : Power Supply
Pin 3 : Relay 2 (NO)
Pin 4 : Relay 2 (COM)
Pin 5 : Relay 1 (NO)
Pin 6 : Relay 1 (COM)
Pin 7 : Loop A
Pin 8 : Loop common and connect to ground $\underset{\underline{L}}{\perp}$
Pin 9 : Loop B
Pin 10 : Relay 1 (NC)
Pin 11 : Relay 2 (NC)
WARNING:
Pin \#8 must be connected to the loop and to ground

## I. THE 3 CONFIGURATIONS

- Configuration A : single loop detector (MATRIX-S) ;
- Configuration B : dual loop detector in independent mode (MATRIX-D with dip switch \#10 OFF) ;
- Configuration C : dual loop detector in combined mode (MATRIX-D with dip switch \#10 ON).

| Dip Switch | Configuration A Single loop |  | Configuration $\mathbf{B}$ Dual loop in independent mode |  | Configuration C Dual loop in combined mode |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | OFF | ON | OFF | ON | OFF | ON |
| DS\#1 | See next table |  | High (loop A) | $\begin{gathered} \text { Low (loop A) } \\ {[\text { High }-30 \%]} \end{gathered}$ | High (loop A) | $\begin{aligned} & \hline \text { Low (loop A) } \\ & \text { [High -30\%] } \\ & \hline \end{aligned}$ |
| DS\#2 |  |  | High (loop B) | $\begin{aligned} & \text { Low (loop B) } \\ & {[\text { High }-30 \%]} \end{aligned}$ | High (loop B) | $\begin{aligned} & \text { Low (loop B) } \\ & \quad \text { [High }-30 \%] \end{aligned}$ |
| DS\#3 | Active mode | Passive mode | Active mode | Passive mode | Active mode | Passive mode |
| DS\#4 | ASB OFF | ASB ON | ASB OFF | ASB ON | ASB OFF | ASB ON |
| DS\#5 | Relay A : <br> Presence on loop A | Relay A : Pulse on loop | Relay A: Presence on loop A | Relay A : <br> Pulse on loop A | Not used | Not used |
| DS\#6 | Relay A : <br> Pulse on loop <br> A <br> entry | Relay A : <br> Pulse on loop A exit | Relay A : <br> Pulse on loop A entry | Relay A : <br> Pulse on loop A <br> Exit | Relay B : <br> Non-Directional mode | Relay B: <br> Directional A $\rightarrow$ B mode |
| DS\#7 | Relay B : Presence on loop A | Relay B : <br> Pulse on loop A | Relay B: Presence on loop B | Relay B : <br> Pulse on loop B | Relay B : <br> Pulse on loop B | Relay B: Pulse on loop A |
| DS\#8 | Relay B : <br> Pulse on loop <br> A <br> entry | Relay B : <br> Pulse on loop A exit | Relay B : <br> Pulse on loop B entry | Relay B : <br> Pulse on loop B exit | Relay B : <br> Pulse on loop entry | Relay B : <br> Pulse on loop exit |
| DS\#9 | 100 ms | 500 ms | 100 ms | 500 ms | 100 ms | 500 ms |
| DS\#10 | Not used | Not used | Independent | Combined mode | Independent | Combined mode |

## II. POTENTIOMETERS



A 10 position dip switch is located on the front of the Matrix single detector. Dip switch $3,5,6,7$, and 8 configure the relay, while dip switch 9 controls the duration of the pulse when the Matrix is configured for pulse operation, (as opposed to presence). Configurations are as follows:

## Dip Switch 3:

OFF= FAIL-SECURE MODE Relay is NOT energized when power is applied. Relay is energized upon detection only. In this mode, the N.O. circuit is open, and the N.C. circuit is closed. Thus, if a closed circuit is required upon detection, one must use the N.O. and COM terminals since they would close upon detection. When the Matrix is NOT powered, it is in the same state as it would be for non-detection.
ON = FAIL-SAFE MODE Relay is energized as soon as power is applied, and de-energizes upon detection or power loss. In this mode, upon powering the detector, the N.O. circuit becomes closed, and the N.C. circuit becomes open. Thus, if a closed circuit is required upon detection, one must use the N.C. and COM terminals, since they would now be OPEN during non-detection, and would close upon detection. When the Matrix is NOT powered, it is in the same state as it would be for detection.

| Detection Status | Fail-Secure Mode (Active Mode) (Relay is not energized upon power-on) Dipswitch 3 OFF | Fail-Safe Mode (Passive Mode) <br> (Relay becomes energized upon power-on) <br> Dipswitch 3 ON |
| :---: | :---: | :---: |
| No Detection | The COM and N.O. terminals are OPEN. COM and N.C. terminals are CLOSED. The relay is de-energized. | The COM and N.O. terminals are CLOSED. COM and N.C. terminals are OPEN. The relay is energized. |
| Detection | The COM and N.O. terminals are CLOSED. COM and N.C. terminals are OPEN. The relay is energized. | The COM and N.O. terminals are OPEN. COM and N.C. terminals are CLOSED. The relay is de-energized. |
| Upon Power Loss $\longrightarrow$ | The COM and N.O. terminals are OPEN. COM and N.C. terminals are CLOSED The relay is de-energized. | The COM and N.O. terminals are OPEN. COM and N.C. terminals are CLOSED. <br> The relay is de-energized. |

DIPSWITCH SEIIINGS

## III. DIP SWITCHES

After each dip switch change the sensor launches a learning process.

| Dip Switch \#1 | Frequency Adjustments of Loop A (see ADJUSTMENTS on the next page) |
| :---: | :---: |
| Dip Switch \#2 | Frequency Adjustments of Loop A (with single loop) or Loop B (with dual loops) |
| Dip Switch \#3 | Relay configuration : active (fail-secure) or passive (fail-safe_ (see above) |
| Dip Switch \#4 | Automatic Sensitivity Boost (ASB option) [recommended for improved truck detection] : During a detection, the sensitivity increases automatically to 8 times the preset sensitivity given by the sensitivity potentiometer adjustment. It is limited to the maximum sensitivity ( $\Delta f=0.005 \%$ ). It goes back to the preset value after detection stops. |
| Dip Switch \#5 | Relay A function : presence or pulse (not used with dual loop in combined mode) |
| Dip Switch \#6 | Relay A Pulse type : entry or exit (used only at pulse function) <br> or Relay B mode (with dual loop in combined mode) (see drawing on next page) <br> - Non-Directional : <br> Relay B provides a pulse according to the dip switches \#7 and \#8 setting. <br> - Directional $\mathrm{A} \rightarrow \mathrm{B}$ : <br> Relay B provides a pulse only if loop A is detecting before loop B. The logic detection takes place according to dip switches \#7 and \#8. <br> Warning : During the detection, the 2 loops have to detect simultaneously for a short period to be able to determine the movement direction. During loop installation make sure the 2 loops are close enough to each other to ensure a common detection (typical 3 feet). |
| Dip Switch \#7 | Relay B function : presence or pulse Or loop selection for relay B pulse : pulse on Loop B or pulse on Loop A (used with dual loop in combined mode) |
| Dip Switch \#8 | Relay B Pulse type : entry or exit (used only at pulse function) |
| Dip Switch \#9 | Pulse duration for both relays (used only at pulse function): 100 ms or 500 ms |
| Dip Switch \#10 | Dual loop mode : independent or combined $\mathrm{A} \rightarrow \mathrm{B}$ (not used with single loop) |


| Frequency adjustment for loop A for single loop detector |  |  |
| :---: | :---: | :---: |
| Dip Switch \#1 | Dip Switch \#2 | Loop frequency |
| OFF | OFF | High |
| ON | OFF | Mid High [High -20\%] |
| OFF | ON | Mid Low [High -25\%] |
| ON | ON | Low $\quad$ High -30\%] |



Green LED shows when the module is powered;
Red LED gives:

- the corresponding loop detection state in normal situation;
- the value of the oscillation frequency measurement or an error message on power ON.

Normally, the red LED stays ON as long as the loop is in a state of detection.
On POWER ON, the sensor measures the oscillation frequency of each loop. The result of this measurement is displayed using the corresponding red LED. The number of flashes indicates the tens value of the frequency. For example 4 short flashes correspond to a frequency between 40 kHz and 49 kHz . After this message the LED goes back to normal display.
If the loop oscillation frequency falls outside the limits ( 20 kHz to 130 kHz ) the red LED displays an error message and the sensor activates the corresponding relay. The blinking frequency shows the type of error according to the next table. The sensor will stay in error mode until the error is cleared and the frequency goes to the right range. Remark: The sensor launches automatically a learning process if the oscillation frequency varies more than $10 \%$ in comparison with the measurement value.

| Loop frequency error | LED display |
| :--- | :--- |
| Oscillation frequency too LOW or loop opened | LED blinking at 1 Hz |
| Oscillation frequency to HIGH | LED blinking faster at 2 Hz |
| Loop shorted or no oscillation | LED blinking slower at 0.5 Hz |


| TROUBLESHOOTNG | SYMPTOM | PROBABLE CAUSE | CORRECTIVE ACTION |
| :---: | :---: | :---: | :---: |
|  | The loop detector will not work. The green LED is off. | There is no power supply to the loop detector. | Check power supply. |
|  | The loop detector will not work. The red LED is flashing slowly ( 0.5 Hz ). | The corresponding loop is shorted. | Check the loop cable. |
|  | The loop detector will not work. The red LED blinks at either 1 Hz or 2 Hz . | The frequency of oscillation falls outside the allowed range. | Adjust frequency with dip switches or change loop turns. |
|  | The loop LED is detecting properly but the contact is not made. | Bad connection of the relay contacts. | Check relay connections. |
|  | Dip switches 5 to 8 are not responding properly. | Their function varies according to dip switch \#10 setting. | Check the appropriate loop mode required and adjust dip switch \#10. |

If after troubleshooting a problem, a satisfactory solution cannot be achieved, please call B.E.A., Inc.
for further assistance during Eastern Standard Time at 1-800-523-2462 from 8am - 5pm.
For after-hours, call East Coast: 1-866-836-1863 / Mid-West: 1-888-308-8843
West Coast: 1-888-419-2564. DO NOT leave any problem unresolved. If you must wait for the following workday to call B.E.A., leave the door inoperable until satisfactory repairs can be made.

NEVER sacrifice the safe operation of the automatic door or gate for an incomplete solution.
Web: www.beasensors.com

